

Multiresolution Cluster Analysis—Addressing Trust in Climate Classifications

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- Can only resolve land.
- Does not adapt to changing climate.
- The cut-offs in model are, to some extent, arbitrary.
- No universal agreement to how many classes there should be.

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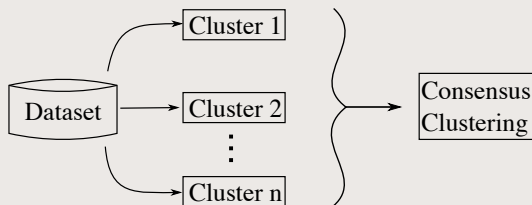


Figure: Many clusterings combined into a single **consensus clustering**.

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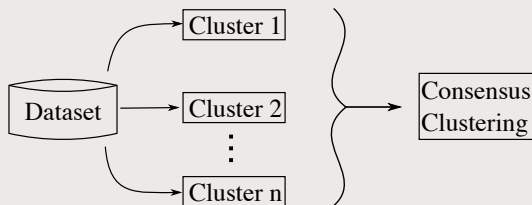


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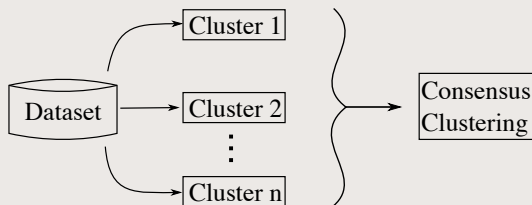


Figure: Many clusterings combined into a single **consensus clustering**.

- Clustering ill-posed - lack measurement of “trust”.
- Dependence on “hidden parameters” - **scale of data**.

Solution

- 1 Leverage discrete wavelet transform to classify across a multitude of scales.

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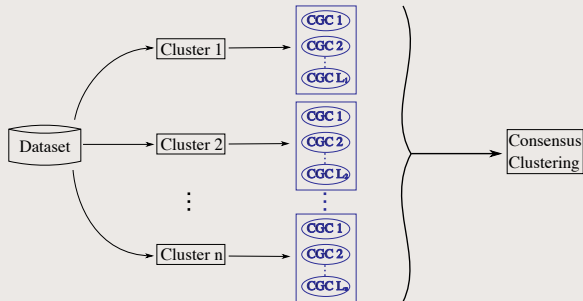
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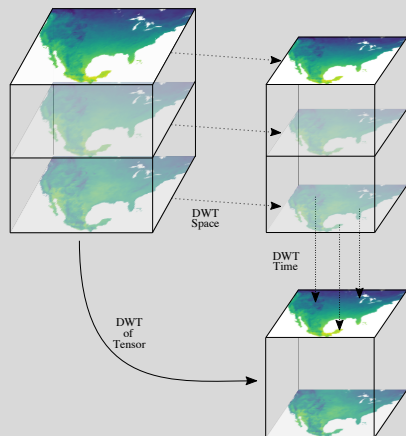
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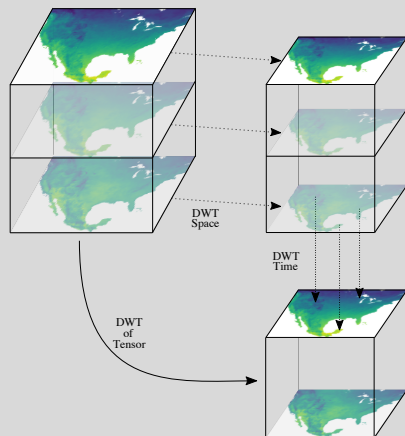
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- The DWT splits a signal into high and low frequency
- Low temporal signal captures climatology (seasons, years, decades), while low spatial signal captures regional features (city, county, state).

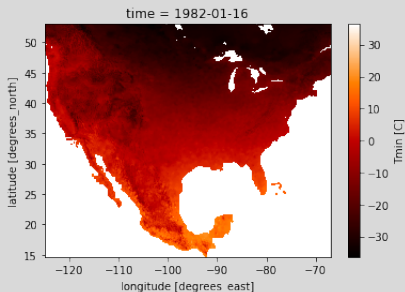


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Definition

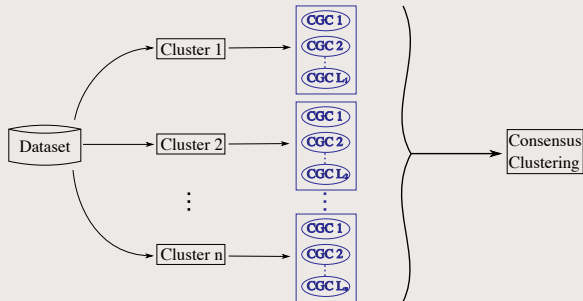
Given partitions of data $U = \{U_j\}_{j=1}^k$, $V = \{V_j\}_{j=1}^l$, the **Mutual Information** $\mathcal{NI}(U, V)$ measures how knowledge of one clustering reduces our uncertainty of the other.

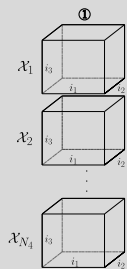


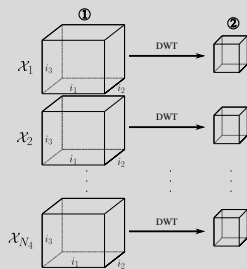
- Gridded climate data set of North America.
- Grid cell is monthly data from 1950-2013, six kilometers across.
- Available variables used: precipitation, maximum temperature, minimum temperature.

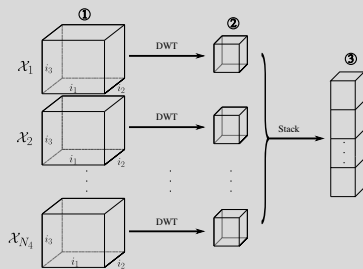
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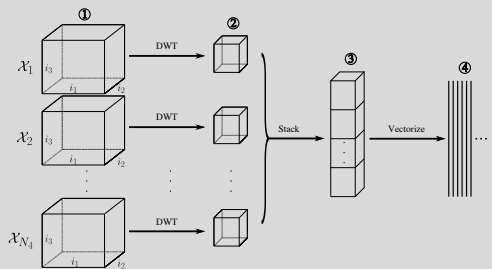
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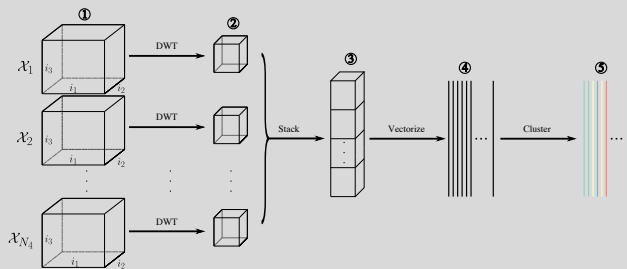


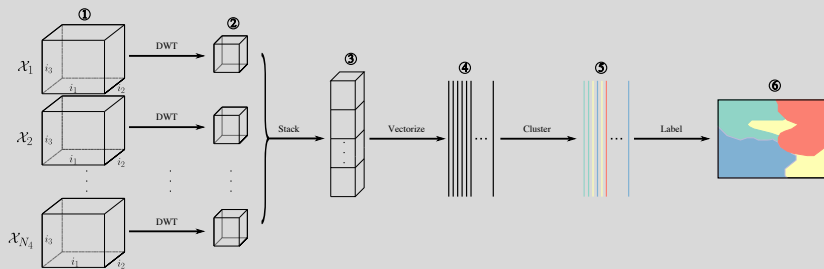












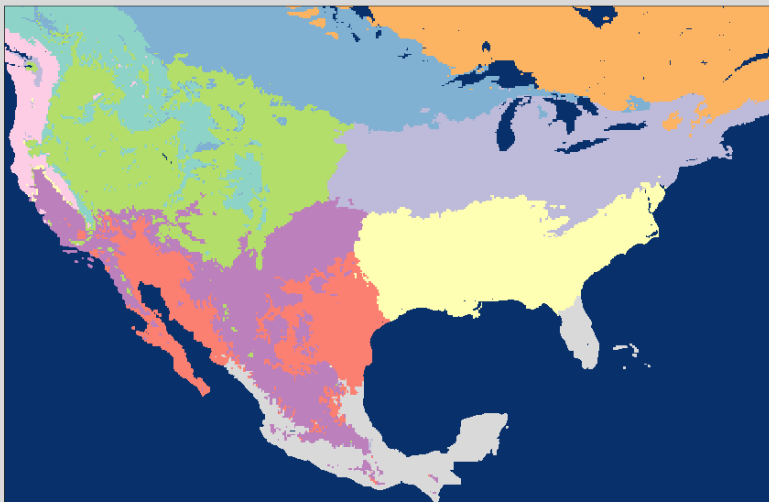


Figure: CGC: K-means $k = 10$, $(l_s, l_t) = (1, 1)$

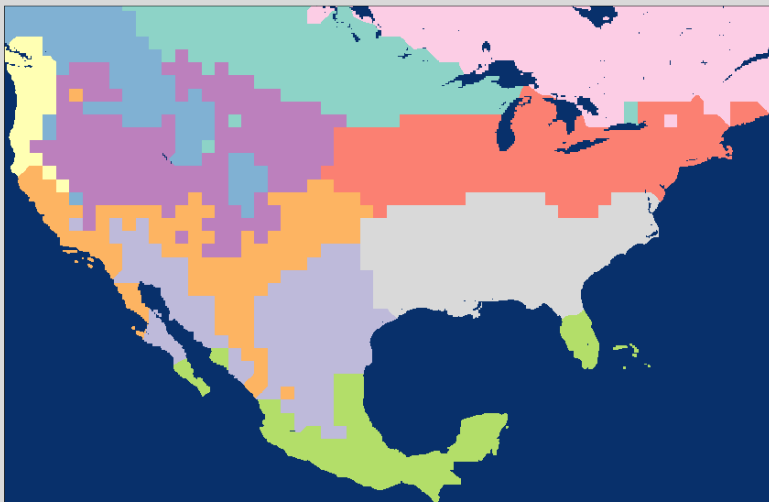


Figure: CGC: K-means $k = 10$, $(l_s, l_t) = (4, 1)$

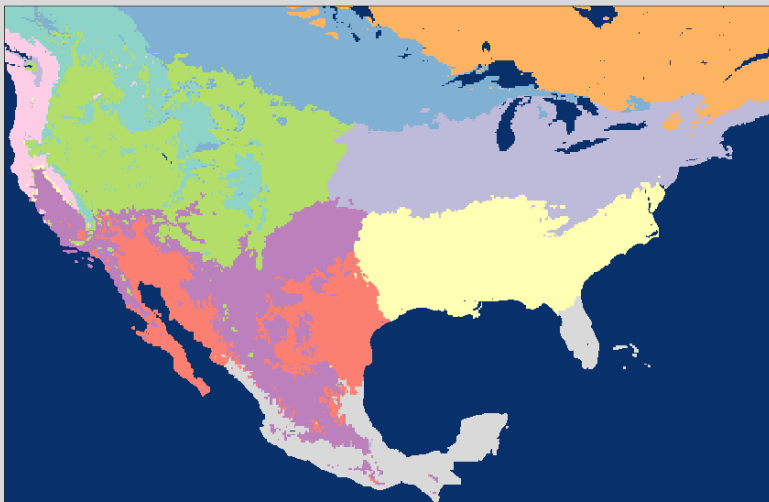


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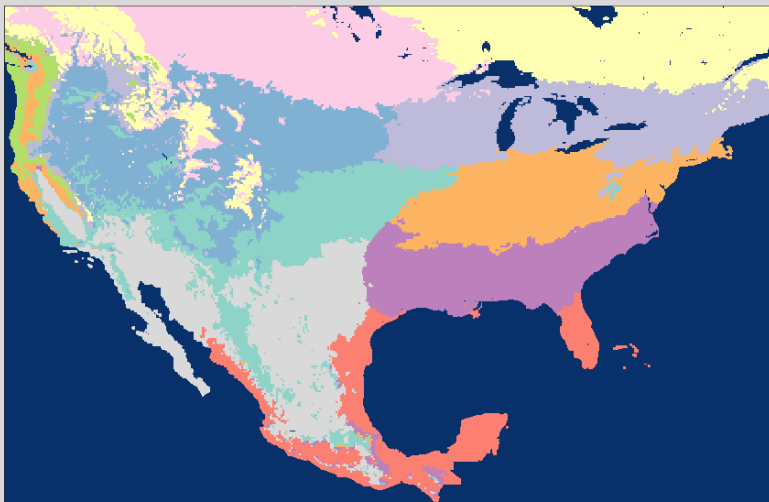


Figure: CGC: K-means $k = 10$, $(l_s, l_t) = (1, 6)$

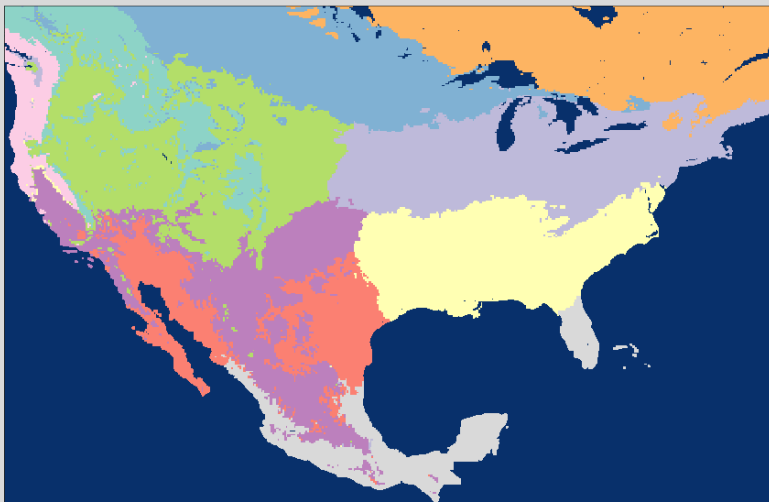


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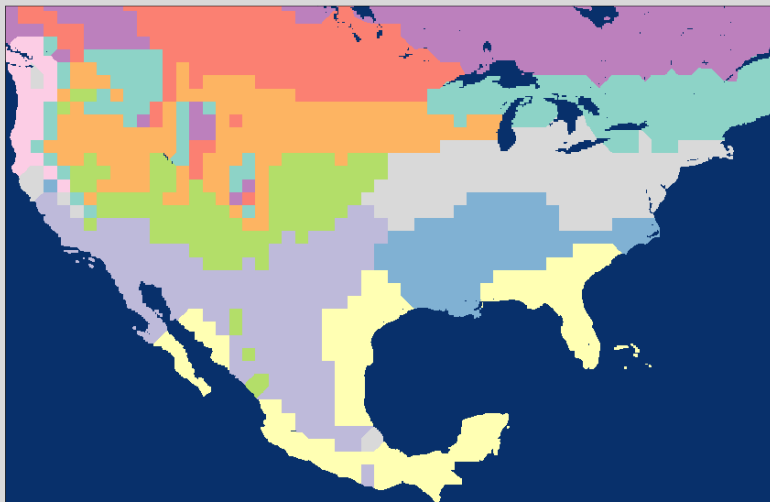
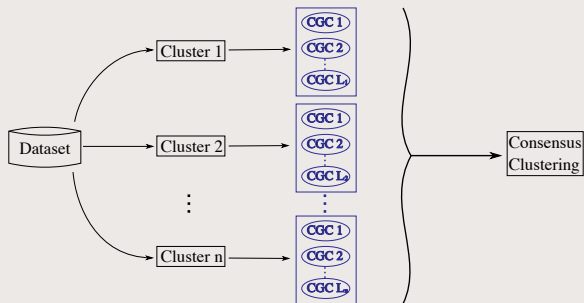
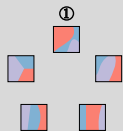


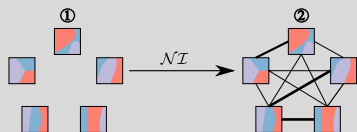
Figure: CGC: K-means $k = 10$, $(l_s, l_t) = (4, 6)$

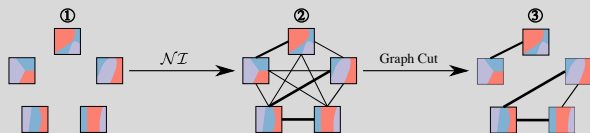
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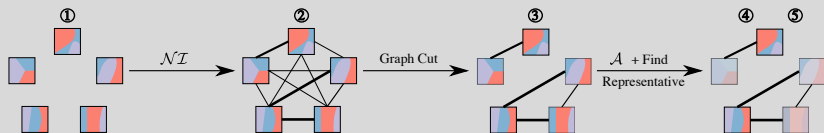
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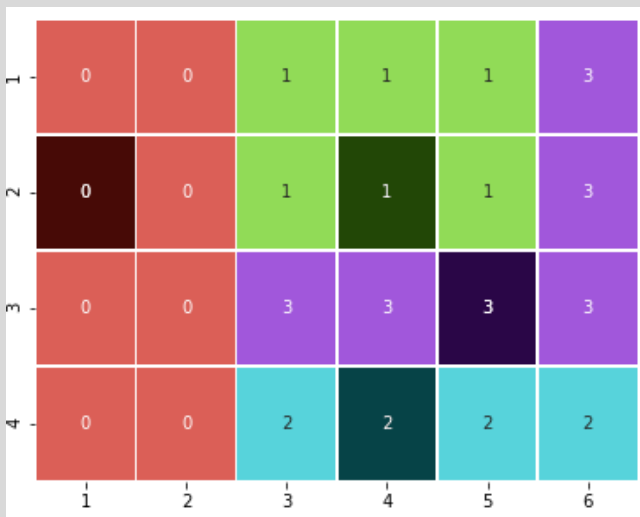
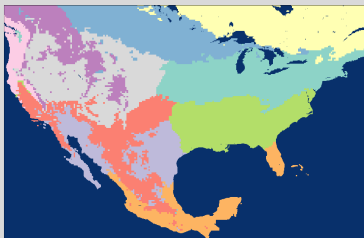
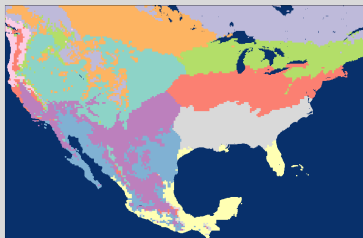


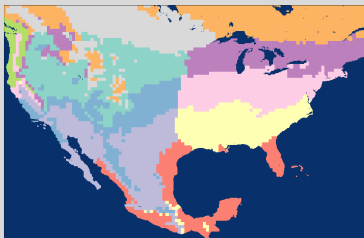
Figure: Results from graph cut algorithm. The highlighted resolutions are the final ensemble. Vertical number = l_s , horizontal bar = l_t .



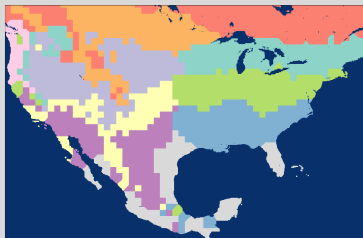
(a) $(l_s, l_t) = (2, 1)$



(b) $(l_s, l_t) = (2, 4)$



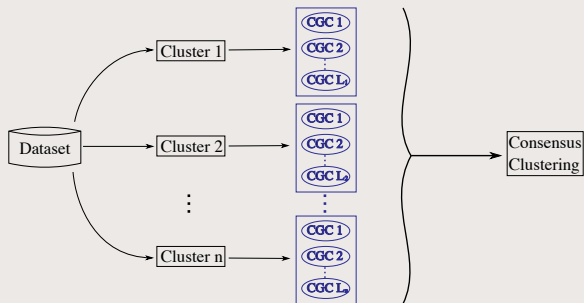
(c) $(l_s, l_t) = (3, 5)$

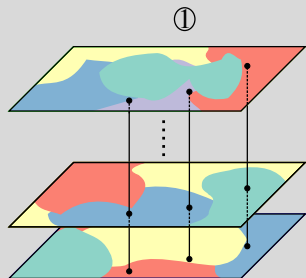


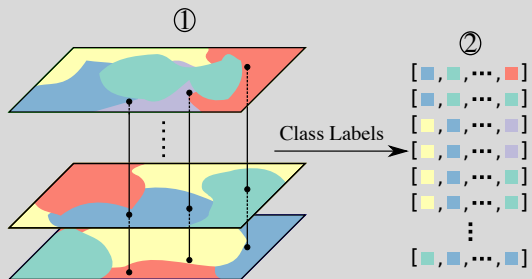
(d) $(l_s, l_t) = (4, 4)$

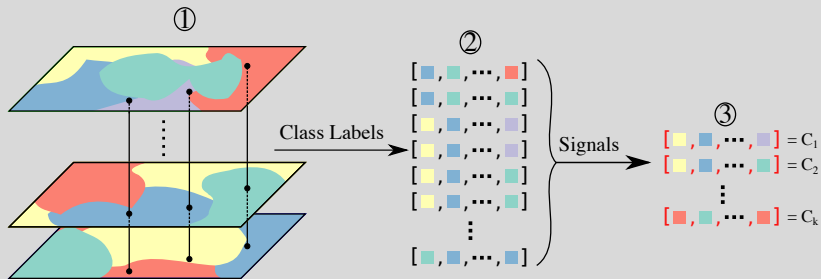
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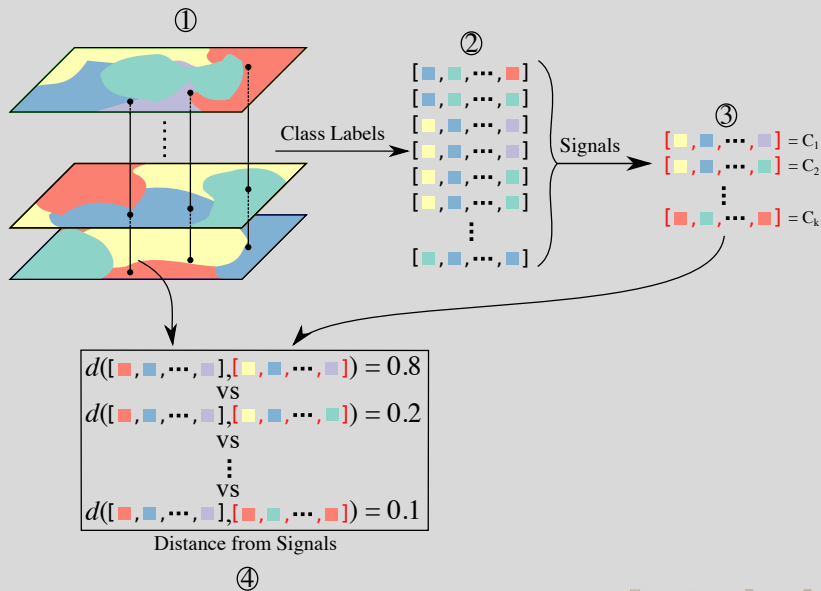
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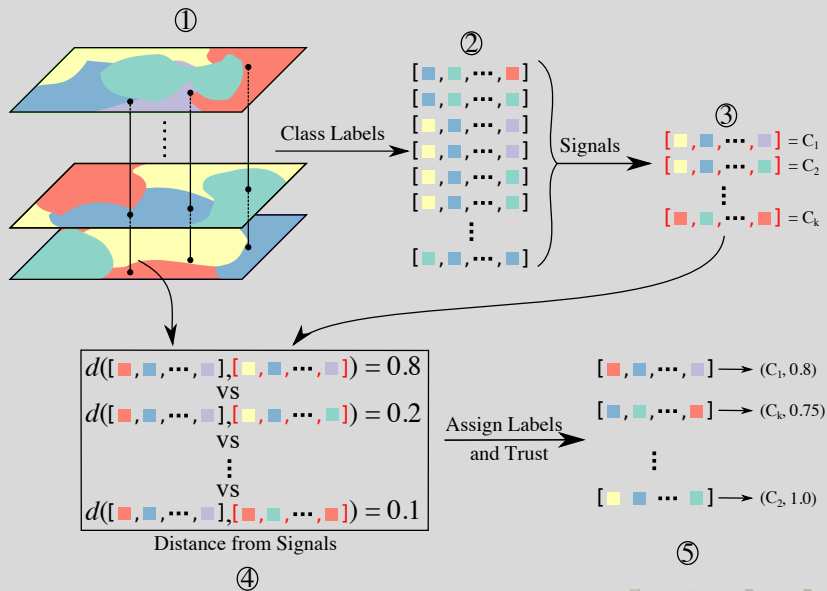












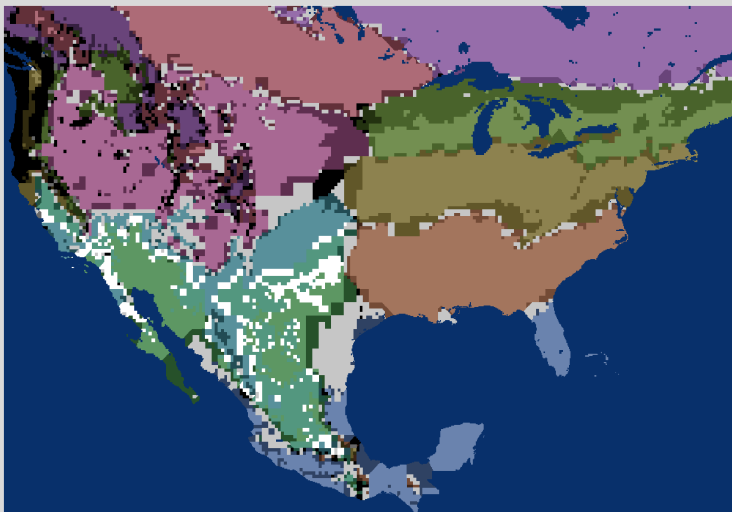


Figure: Consensus clustering from reduced ensemble of clusters for $k=10$, along with the trust. Grey = multi-class. Darker hue = lower trust.

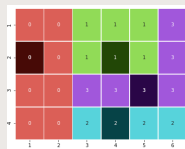
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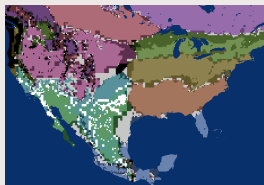
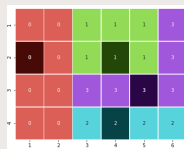
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- Mutual information allows us to effectively represent the diversity across all scales.
- Using this reduced ensemble, we produce a fuzzy clustering that has an interpretable trust metric at each point in space.



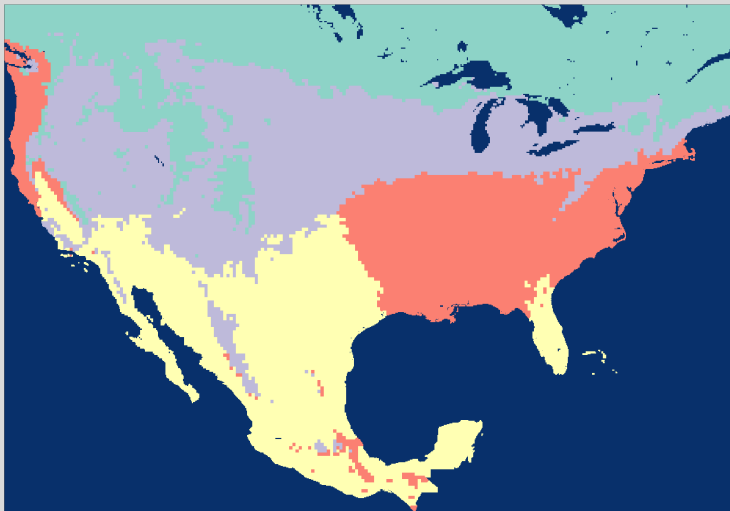


Figure: CGC: K-means $k = 4$, $(l_s, l_t) = (2, 3)$

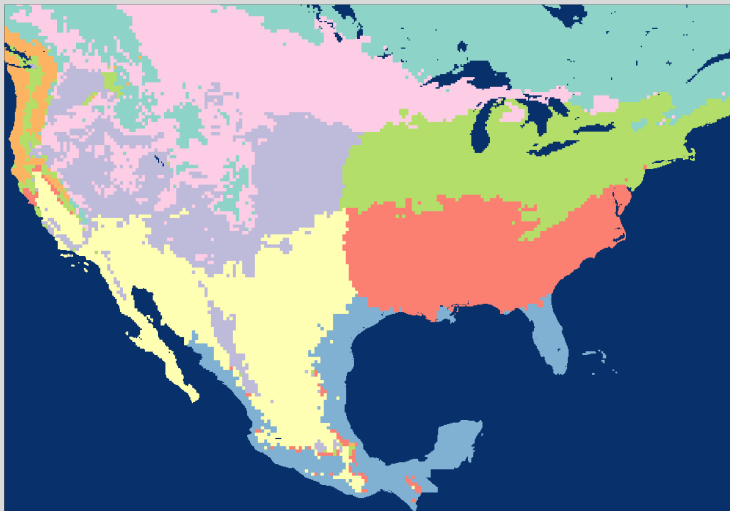


Figure: CGC: K-means $k = 8$, $(l_s, l_t) = (2, 3)$

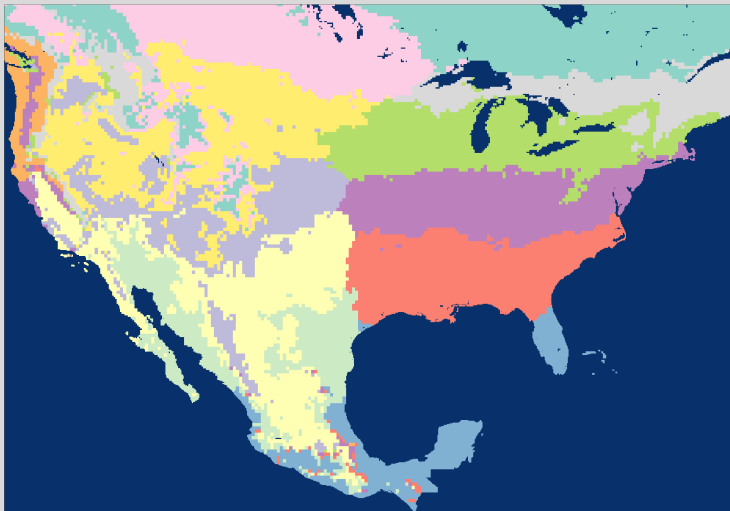


Figure: CGC: K-means $k = 12$, $(l_s, l_t) = (2, 3)$

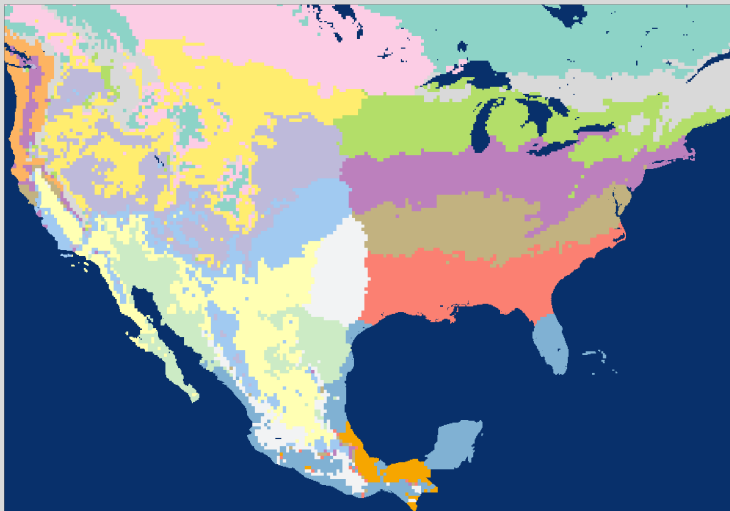


Figure: CGC: K-means $k = 16$, $(l_s, l_t) = (2, 3)$